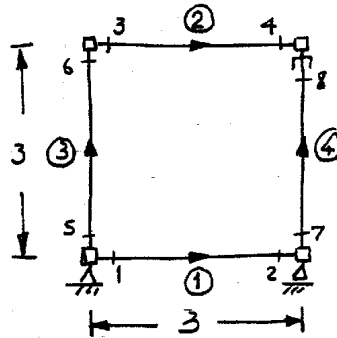


PROBLEMA PROPOSTO 3

①

Orientação e linearização



Esforos e deformações independentes

$$\tilde{X}_1^t = \{M_1 \ M_2 \ N_2\}$$

$$\tilde{X}_2^t = \{M_3 \ M_4 \ N_4\}$$

$$\tilde{X}_3^t = \{M_5 \ M_6 \ N_6\}$$

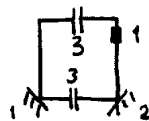
$$\tilde{X}_4^t = \{M_7 \ M_8\}$$

Hiperestática

$$\alpha_e = 3 - 3 = 0$$

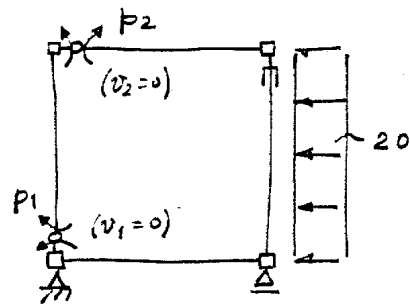
$$\alpha_i = 3 - 1 = 2$$

$$\alpha = 2$$



$$\alpha = (3+3) - (1+2+1)$$

Estática - base



Solução particular - Esforços $\tilde{X}_0$



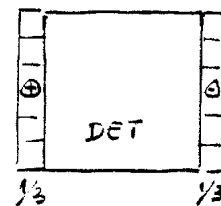
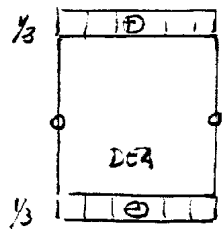
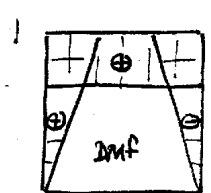
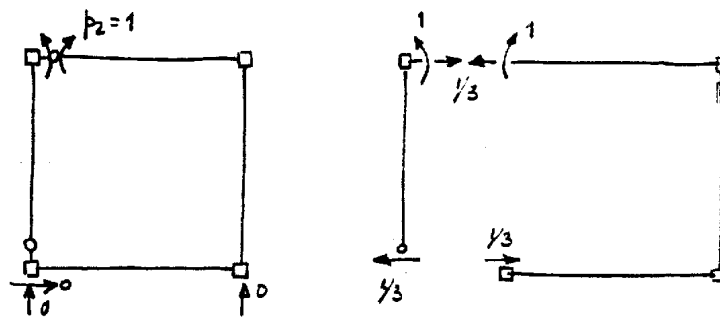
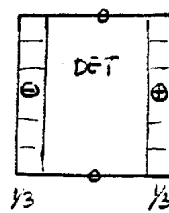
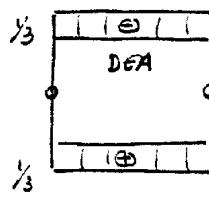
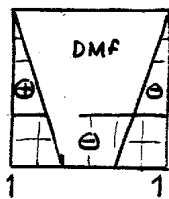
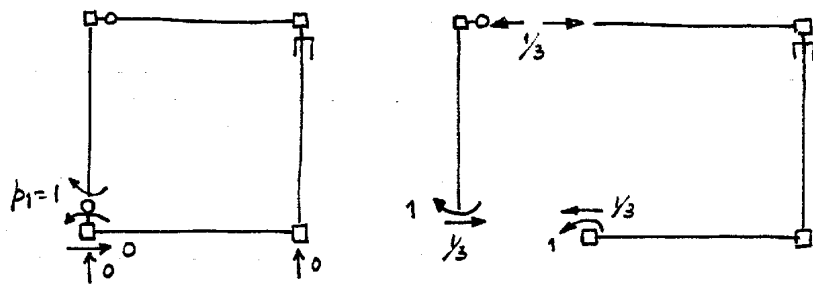
$$\tilde{X}_0^t = \left\{ \begin{array}{ccc|ccc|ccc} 0 & 90 & -60 & 0 & 0 & 0 & 0 & 0 & 0 \\ M_1 & M_2 & N_2 & M_3 & M_4 & N_4 & M_5 & M_6 & N_6 \\ 90 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right\}$$

Solução particular - Deformações $\underline{u}_0$

$$\underline{u}_0^t = \frac{1}{EI} \left\{ \begin{array}{ccc|ccc|ccc} 45 & 90 & -6 & 0 & 0 & 0 & 0 & 0 & 0 \\ \theta_1 & \theta_2 & e_2 & \theta_3 & \theta_4 & e_4 & \theta_5 & \theta_6 & e_6 \\ 67.5 & 22.5 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right\}$$

Solucan complementat - Estren $X_c = B_k$

(2)



③

$$\underline{X}_c = \underline{B} \cdot \underline{P}$$

M1
M2
N2

 $=$

-1	0
-1	0
1/3	-1/3

 $\cdot$

P1
P2

M3
M4
N4

 $=$

0	1
0	1
-1/3	1/3

 $\rightarrow \underline{B}_{(1)}$

M5
M6
N6

 $=$

1	0
0	1
0	0

 $\rightarrow \underline{B}_{(2)}$

M7
M8

 $=$

-1	0
0	-1

 $\rightarrow \underline{B}_{(3)}$

Nota: $\underline{u} = \underline{B}^T \underline{u}$

$$\underline{u} = \sum_{m=1}^4 \underline{B}_m^T \underline{u}_m$$

Soluc es complementares - Deformac es $\underline{u}_{m_c} = \underline{f}_m \underline{X}_{m_c} = \underline{f}_m \underline{B}_m \underline{P}$

Bases 1, 2, 3 $\underline{f}_m = 1/EI$

1	1/2	0
1/2	1	0
0	0	1/30

Bases 4 $\underline{f}_{(4)} = 1/EI$

1	1/2
1/2	1

$$\underline{u}_{(1)c} = \begin{bmatrix} \theta_1 \\ \theta_2 \\ e_2 \end{bmatrix}_c = \frac{1}{EI} \begin{bmatrix} -3/2 & 0 \\ -3/2 & 0 \\ 1/30 & -1/30 \end{bmatrix} \begin{bmatrix} P1 \\ P2 \end{bmatrix}$$

$$\underline{u}_{(2)c} = \begin{bmatrix} \theta_3 \\ \theta_4 \\ e_4 \end{bmatrix}_c = \frac{1}{EI} \begin{bmatrix} 0 & 3/2 \\ 0 & 3/2 \\ -1/30 & 1/30 \end{bmatrix} \begin{bmatrix} P1 \\ P2 \end{bmatrix}$$

4

$$u_{\theta_c} = \begin{bmatrix} \theta_5 \\ \theta_6 \\ u_6 \end{bmatrix}_c = \frac{1}{EI} \begin{bmatrix} 1 & 1/2 \\ 1/2 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} p_1 \\ p_2 \end{bmatrix}$$

$$u_{\theta_c} = \begin{bmatrix} \theta_7 \\ \theta_8 \\ u_8 \end{bmatrix}_c = \frac{1}{EI} \begin{bmatrix} -1 & -1/2 \\ -1/2 & -1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} p_1 \\ p_2 \end{bmatrix}$$

Solução particular - Deslocamentos $v_0 = B^T u_0 = \sum B_m^T u_m$

$$v_0 = \sum_m v_m, \quad v_m = B_m^T u_m$$

$$v_0 = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}_0 = \frac{1}{EI} \begin{bmatrix} -204.5 \\ -20.5 \end{bmatrix} \quad (\text{rad})$$

Solução complementar - Deslocamentos $v_c = B^T v_c = \sum B_m^T v_m$

$$v_c = \sum B_m^T F_m B_m B ; \quad v_c = \bar{F} \bar{p} ; \quad \bar{F} = \sum B_m^T F_m B_m ; \quad F_m = B_m^T F B_m$$

$$\bar{F} = \frac{1}{45EI} \begin{bmatrix} 226 & 44 \\ 44 & 226 \end{bmatrix} \quad (\text{rad}^2/\text{Nm})$$

Equação de Movimento das barras $v = v_c + v_0 = \bar{F} \bar{p} + v_0 = 0$

$$\frac{1}{45EI} \begin{bmatrix} 226 & 44 \\ 44 & 226 \end{bmatrix} \begin{bmatrix} p_1 \\ p_2 \end{bmatrix} + \frac{1}{EI} \begin{bmatrix} -204.5 \\ -20.5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} p_1 \\ p_2 \end{bmatrix} = \begin{bmatrix} -41.417 \\ -3.997 \end{bmatrix} \quad (\text{rad})$$

Form independent $X_M = X_{M_0} + X_{M_1} = B_M P_1 + X_{M_0}$ (5)

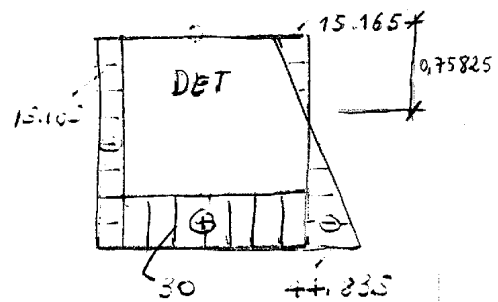
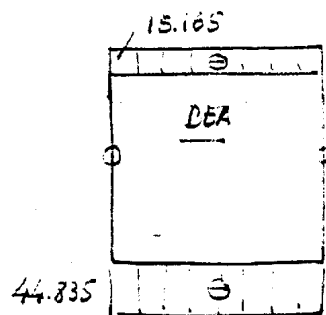
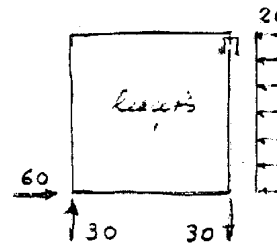
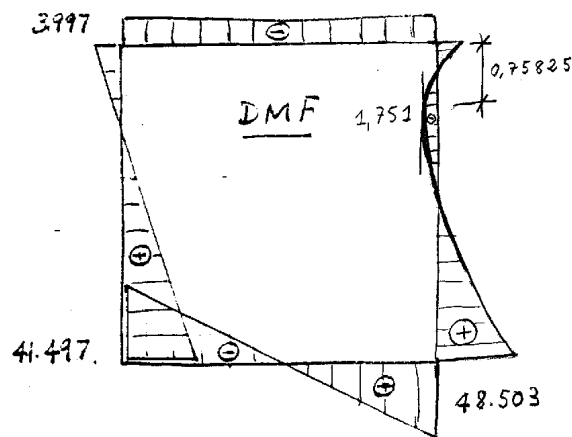
$$X_0 = \begin{array}{|c|} \hline M_1 \\ \hline M_2 \\ \hline N_2 \\ \hline \end{array} = \begin{array}{|c|} \hline -41.497 \\ \hline +48.503 \\ \hline -44.835 \\ \hline \end{array}$$

$$X_0 = \begin{array}{|c|} \hline M_3 \\ \hline M_4 \\ \hline N_4 \\ \hline \end{array} = \begin{array}{|c|} \hline -3.997 \\ \hline -3.997 \\ \hline -15.165 \\ \hline \end{array}$$

$$X_0 = \begin{array}{|c|} \hline M_5 \\ \hline M_6 \\ \hline N_6 \\ \hline \end{array} = \begin{array}{|c|} \hline 41.497 \\ \hline -3.997 \\ \hline 0 \\ \hline \end{array}$$

$$X_0 = \begin{array}{|c|} \hline M_7 \\ \hline M_8 \\ \hline \end{array} = \begin{array}{|c|} \hline +48.503 \\ \hline 3.997 \\ \hline \end{array}$$

Diagramas de apoyo



⑥

Deformations independentes $u_m = u_{m1} + u_{m2} = \frac{1}{EI} B_m P_m + u_{mo}$

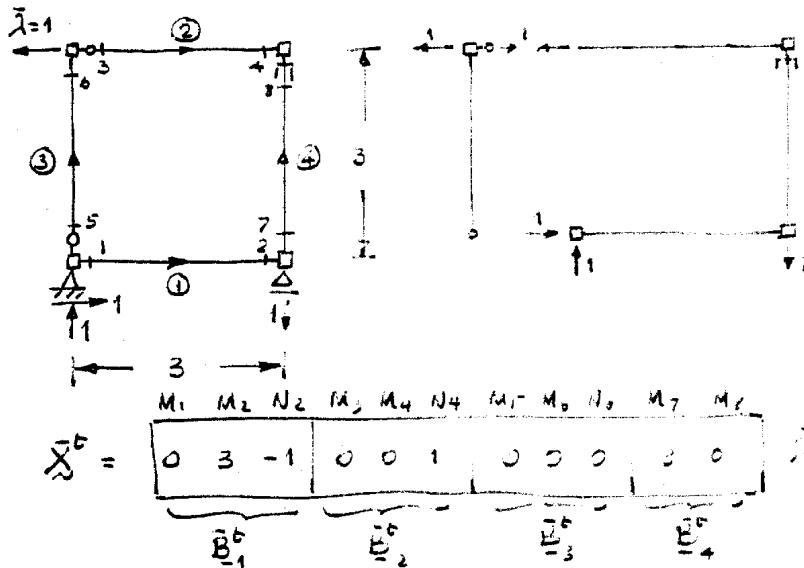
$$u_D = \begin{bmatrix} \theta_1 \\ \theta_2 \\ e_2 \end{bmatrix} = \frac{1}{EI} \begin{bmatrix} -17.246 \\ 27.754 \\ -4.434 \end{bmatrix}$$

$$u_D = \begin{bmatrix} \theta_3 \\ \theta_4 \\ e_4 \end{bmatrix} = \frac{1}{EI} \begin{bmatrix} -5.996 \\ -5.996 \\ -1.516 \end{bmatrix}$$

$$u_D = \begin{bmatrix} \theta_5 \\ \theta_6 \\ e_6 \end{bmatrix} = \frac{1}{EI} \begin{bmatrix} +39.499 \\ +16.751 \\ 0 \end{bmatrix}$$

$$u_D = \begin{bmatrix} \theta_7 \\ \theta_8 \end{bmatrix} = \frac{1}{EI} \begin{bmatrix} +28.001 \\ +5.749 \end{bmatrix}$$

Deslocamento horizontal do nó C $\delta = \bar{E}^C u = \sum \bar{E}_m^C u_m$



$$\delta_H^C = 170.233/EI$$