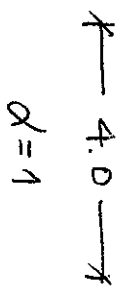
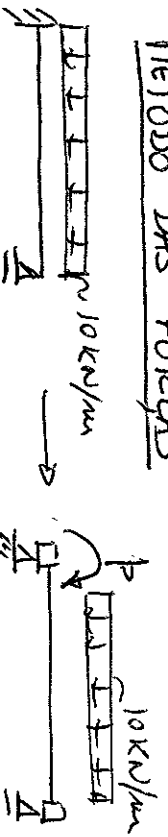


MÉTODO DAS FORÇAS

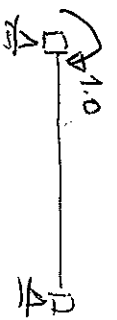


$\alpha = 1$



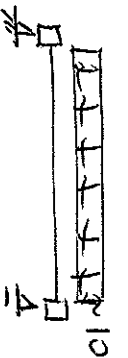
(ESCOLHA DO SISTEMA - BASE)
 α LIBERTAÇÕES

SOLUÇÃO COMPLEMENTAR



$$\bar{X}_c = \begin{bmatrix} 1.0 \\ 0.0 \\ 0.0 \end{bmatrix} \times P$$

SOLUÇÃO PARTICULAR



$$\bar{X}_0 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

SOBREPÓSICÃO

$$\bar{X} = \bar{B}P + \bar{X}_0 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} P + \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

CONS DETERMINAR O VALOR DE P?

$$\bar{u}_c = F \bar{X}_c = \frac{4}{6EI} \begin{bmatrix} 2 & 10 \\ 1 & 20 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} P = \frac{4}{6EI} \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} P$$

$$\bar{u}_0 = F \bar{X}_0 + \bar{u} = \frac{10 \times 4^3}{24EI} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\theta_{Ac} = B^T \bar{u}_c = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \frac{4}{6EI} \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} P$$

$$\theta_{Ac} = \frac{4}{6EI} \times 2P = \frac{4}{3EI} P$$

$$\theta_{Ac} = B^T \bar{u}_c = B^C (F \bar{X}_c)$$

$$\theta_{Ac} = \frac{B^T F}{B} P$$

$$\theta_{A0} = B^C \bar{u}_0 = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \frac{10 \times 4^3}{24EI} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\theta_{A0} = \frac{10 \times 4^3}{24EI}$$

$$\theta_{A0} = B^T \bar{u}_0$$

$$\theta_{A0} = \frac{B^C F \bar{X}_0}{B^T \bar{u}}$$

$$\theta_{Ac} + \theta_{A0} = 0$$

$$\frac{4}{3EI} P + \frac{10 \times 4^3}{24EI} = 0$$

$$P = -\frac{10 \times 4^3}{24} \times \frac{3}{4}$$

$$P = -\frac{10 \times 4^2}{8}$$

$$P = -20$$